

Lixel K2

The Gold Standard in
Lightweight Scanning —
Handheld SLAM LiDAR
Scanner



PRODUCT SPECIFICATION SHEET

HARDWARE

Power input	14.4 V
Power consumption	< 20 W
Weight ^[1]	Approx. 1,200 g
Data interface	USB 3.1 Gen2
Internal storage	eMMC 512 GB
RTK module	Supported (built-in)
GNSS	BDS: B1I, B3I, B1C, B2a, B2b GPS: L1C/A, L1C, L2C, L2P(Y), L5 GLONASS: G1, G2, G3 Galileo: E1, E5a, E5b, E6 QZSS: L1C/A, L1C, L2C, L5, L6 SBAS: L1C/A
WiFi	IEEE 802.11 a/b/g/n/ac — 2.4–2.4835 GHz (2.4 GHz ISM Band); 5.15–5.25, 5.25–5.35, 5.47–5.73, 5.735–5.835 GHz (5 GHz ISM Band)
Bluetooth	v2.1+EDR / 3.0+HS / 4.2 / 5.0
Housing	Aviation-grade aluminum
Battery life	1.5 hours

OPERATING ENVIRONMENT

Temperature range	–20 °C to 50 °C
Ingress protection	IP54

BATTERY

Power method	Clip-on battery
Battery capacity	1,900 mAh

LIDAR MODULE

Laser class	Class 1 / 905 nm
Scan range	≥ 40 m @10% reflectivity; 100 m maximum range
Field of view	360° x –7° to +52°
Scan mode	Mobile
Point rate	200,000 pts/s

VISION MODULE

Camera count	3 (2 × fisheye, 1 × forward-facing)
Panoramic FOV	200° × 200°
Forward camera FOV	100° × 85°
Camera resolution	4000 × 3000
CMOS sensor size	1/2"
Shutter type	Rolling shutter

ACCURACY

Absolute accuracy, elevation (RMSE) ^[2]	3 cm
Absolute accuracy, horizontal (RMSE) ^[2]	3 cm
Relative accuracy (RMSE) ^[3]	1 cm
Repeatability ^[4]	2 cm
Post-processed point cloud thickness	≤ 1 cm
Real-time absolute accuracy, elevation (RMSE) ^[5]	3 cm
Real-time absolute accuracy, horizontal (RMSE) ^[5]	3 cm

FEATURE HIGHLIGHT

Guided scan assistance with real-time quality check	Supported
In-App measurements and point cloud file sharing	Supported
Real-time dynamic object removal, filtering & coloring	Supported
Point cloud, Mesh, 3DGS output from single scan	Supported

OUTPUT FORMATS

Point cloud	.las .rcp .e57 .ply .ilas
Image	.jpg
Mesh	.osgb .obj
3DGS	.lcc2 .lcc .ply
Others	3D Tiles .usd

ACCESSORIES

Phone mount	Included
Control point base	Included
Extension pole & adapter kit	Optional

[1] Includes battery and base; excludes other accessories.

[2] Measured under open sky, no multipath interference, optimal GNSS geometry, and favorable atmospheric conditions.

[3] Point-to-point distance within 10 m; measured under laboratory conditions. Actual performance may vary.

[4] Measured under laboratory conditions. Actual performance may vary.

[5] Measured under open sky, no multipath interference, optimal GNSS geometry, and favorable atmospheric conditions. Supports WGS84 and CGCS2000 only.

CONTACT US

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